

Input variables

Target

$$X = [p_T, \eta, \phi, \rho]$$

Simulation

y_1

X

y_1^{corr}

y_2

X

y_1^{corr}

y_2^{corr}

y_3

⋮

⋮

X

y_1^{corr}

⋮

y_{n-1}^{corr}

y_n