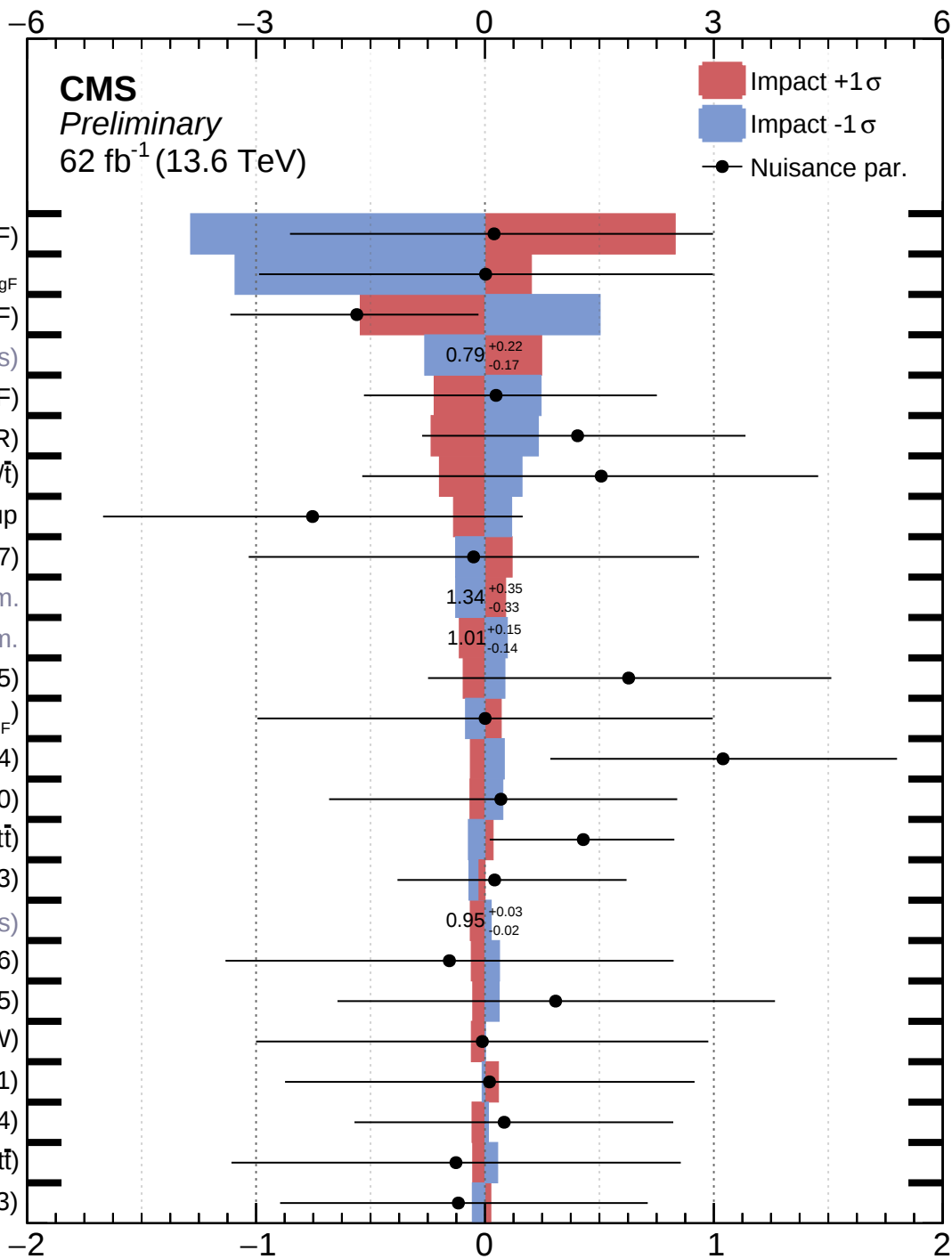


Nuisance parameter $(\theta_{\text{post}} - \theta_{\text{pre}}) / \Delta\theta$